

Physics 221A: QFT I
w/ Prof. Joe Polchinski

Solution Set #1

O/ I'll use a/a^\dagger instead of χ/χ^\dagger to avoid confusion with x .

First we want to show

$$|x_1 \dots x_n\rangle = a_{x_1}^\dagger \dots a_{x_n}^\dagger |0\rangle, \text{ where } a_x^\dagger \equiv a^\dagger(x).$$

This is just the definition of the state with particles at x_1, \dots, x_n , but we can check that it has the properties we'd like it to have also defined this way.

First, if the particles are bosons (resp. fermions), $|x_1, \dots, x_n\rangle$ should be (anti)symmetric under exchanging any of the x_i . This follows immediately from the canonical (anti)commutation relations for the $a_{x_i}^\dagger$. Let σ be a map permuting the numbers $1 \dots n$, i.e. $\sigma \in \text{Perm}(n)$.

Then $|x_{\sigma(1)} \dots x_{\sigma(n)}\rangle = (\det \sigma)^F |x_1 \dots x_n\rangle$, where F is the fermion # = $\begin{cases} 0 & \text{bosons} \\ 1 & \text{fermions} \end{cases}$, and $\det \sigma$ is $+1$ if $\sigma(1) \dots \sigma(n)$ is an even permutation of $1 \dots n$, -1 if it's odd.

If the particle is bosonic, symmetry under particle exchange follows immediately because the a^\dagger 's commute.

If we have a fermion, we get the more complicated action (*) from the anticommutation relations, since if σ is odd, we have to anticommute an odd # of times, picking up a -1 .

o cont'd

We also want $a_x |x_1 \dots x_n\rangle \sim \sum_j \delta(x-x_j) |x_1 \dots x_j \dots x_n\rangle$

So that $a_x |x_1 \dots x_n\rangle$ is the state with $n-1$ particles at $x_1 \dots x_j \dots x_n$,

and $a_x^\dagger a_x |x_1 \dots x_n\rangle = \sum_j \delta(x-x_j) |x_1 \dots x_n\rangle$, so that $|x_1 \dots x_n\rangle$

is an eigenstate of the number operator, varying away from the x_i and returning the state (with the usual δ -function normalization) when $x=x_i$.

All that remains is to compute. The upper sign is always for bosons.

$$\begin{aligned} a_x^\dagger a_x |x_1 \dots x_n\rangle &= a_x^\dagger a_x a_{x_1}^\dagger \dots a_{x_n}^\dagger |0\rangle \\ &= a_x^\dagger [a_x, a_{x_1}^\dagger] a_{x_2}^\dagger \dots a_{x_n}^\dagger |0\rangle \pm a_x^\dagger a_{x_1}^\dagger a_x a_{x_2}^\dagger \dots a_{x_n}^\dagger |0\rangle \\ &= a_x^\dagger [a_x, a_{x_1}^\dagger] a_{x_2}^\dagger \dots a_{x_n}^\dagger |0\rangle \pm a_x^\dagger a_{x_1}^\dagger [a_x, a_{x_2}^\dagger] a_{x_3}^\dagger \dots a_{x_n}^\dagger |0\rangle \\ &\quad + \dots (\pm)^{n-1} a_x^\dagger a_{x_1}^\dagger \dots [a_x, a_{x_n}^\dagger] |0\rangle \end{aligned}$$

(where the series terminates because a annihilates the vacuum)

$$\begin{aligned} &= a_x^\dagger \sum_{j=1}^n \delta(x-x_j) a_{x_1}^\dagger \dots a_{x_j}^\dagger \dots a_{x_n}^\dagger |0\rangle \cdot (\pm)^{j-1} \\ &= \sum_{j=1}^n \delta(x-x_j) a_{x_1}^\dagger \dots a_{x_j}^\dagger \dots a_{x_n}^\dagger |0\rangle \\ &= \sum_{j=1}^n \delta(x-x_j) |x_1 \dots x_n\rangle \checkmark \end{aligned}$$

In the second to last line, I (anti)commuted a_x^\dagger $j-1$ times to get it in the j th position, which killed the $(\pm 1)^{j-1}$ in the previous line. I also used the properties of the δ function in setting $a_x^\dagger = a_{x_j}^\dagger$.

Let $\psi(x_1, \dots, x_n, t)$ be the quantum-mechanics position-space wave function.

Here we will take $\psi \in \mathbb{C}$, but more generally ψ could be valued in an arbitrary group manifold in some representation of the gauge symmetry group.

Then

We want to show that if $i\hbar \frac{\partial}{\partial t} \psi = \left[\sum_j \left(\frac{\hbar^2}{2m} \nabla_j^2 + U(x_j) \right) + \sum_{j,k} V(x_j - x_k) \right] \psi$,

then the QFT state $|\psi\rangle \equiv \int \prod_i dx_i a_{x_i}^\dagger \psi(x_1, \dots, x_n, t) |0\rangle$

obeys $i\hbar \frac{\partial}{\partial t} |\psi\rangle = \left[\int dx a_x^\dagger \left(\frac{\hbar^2}{2m} \nabla_x^2 + U(x) \right) a_x + \frac{1}{2} \int dx dy a_x^\dagger a_y^\dagger V(x-y) a_y a_x \right] |\psi\rangle$

HeFT

I'll do this piece by piece.

$$\int dx a_x^\dagger \nabla_x^2 a_x |\psi\rangle = \int dx \prod_i dx_i a_x^\dagger \nabla_x^2 a_x a_{x_1}^\dagger \dots a_{x_n}^\dagger \psi(x_1, \dots, x_n, t) |0\rangle$$

$$= \sum_j \int dx \prod_i dx_i \psi(x_1, \dots, x_n, t) a_x^\dagger \nabla_x^2 \delta(x - x_j) a_{x_1}^\dagger \dots a_{x_j}^\dagger \dots a_{x_n}^\dagger |0\rangle \cdot \left(\frac{\pm 1}{\pm 1} \right)^{j-1}$$

by (anti)commuting a_x in to the right in steps ↑ formulas

$$= \sum_j \int dx \prod_i dx_i \nabla_x^2 \psi(x_1, \dots, x_n, t) a_x^\dagger \delta(x - x_j) a_{x_1}^\dagger \dots a_{x_j}^\dagger \dots a_{x_n}^\dagger |0\rangle \cdot (\pm 1)^{j-1}$$

under integration by parts and using the boundary condition regularly ψ to fall off sufficiently fast @ ∞

$$= \sum_j \int \prod_i dx_i \nabla_{x_j}^2 \psi(x_1, \dots, x_n, t) a_{x_j}^\dagger a_{x_1}^\dagger \dots a_{x_j}^\dagger \dots a_{x_n}^\dagger |0\rangle (\pm 1)^{j-1}$$

by performing the x -integral

1 cont'd

$$= \sum_j \int \prod_i dx_i \nabla_{x_j}^2 \psi(x_1, \dots, x_n, t) a_{x_1}^\dagger \dots a_{x_n}^\dagger |0\rangle$$

upon (left) commuting $a_{x_j}^\dagger$ to the right $j-1$ times. Next,

$$\int dx a_x^\dagger U(x) a_x |\psi\rangle = \sum_j \int \prod_i dx_i U(x_j) \psi(x_1, \dots, x_n, t) a_{x_1}^\dagger \dots a_{x_n}^\dagger |0\rangle$$

by identical logic, only we don't have to integrate by parts to get ∇^2 off the δ -fn.

Even the V term is not so bad if we keep our heads on straight:

$$\frac{1}{2} \int dx dy V(x-y) a_x^\dagger a_y^\dagger a_y a_x \int \prod_i dx_i a_{x_1}^\dagger \dots a_{x_n}^\dagger \psi(x_1, \dots, x_n, t) |0\rangle$$

$$= \frac{1}{2} \sum_j \int dx dy \prod_i dx_i a_{x_1}^\dagger a_{x_2}^\dagger a_y^\dagger V(x-y) \delta(x-x_j) a_{x_1}^\dagger \dots a_{x_j}^\dagger \dots a_{x_n}^\dagger |0\rangle (\pm 1)^{j-1}$$

$$= \sum_{k < j} \int dx dy \prod_i dx_i a_{x_1}^\dagger a_{x_2}^\dagger V(x-y) \delta(x-x_j) \delta(y-x_k) a_{x_1}^\dagger \dots a_{x_k}^\dagger \dots a_{x_j}^\dagger \dots a_{x_n}^\dagger |0\rangle (\pm 1)^{j+k}$$

↑ make sure you understand this part - I saved a lot of work here

$$= \sum_{k < j} \int \prod_i dx_i a_{x_1}^\dagger a_{x_2}^\dagger V(x_j - x_k) a_{x_1}^\dagger \dots a_{x_k}^\dagger \dots a_{x_j}^\dagger \dots a_{x_n}^\dagger |0\rangle (\pm 1)^{j+k}$$

$$= \sum_{k < j} \int \prod_i dx_i V(x_j - x_k) a_{x_1}^\dagger \dots a_{x_n}^\dagger \psi(x_1, \dots, x_n, t)$$

$$\Rightarrow H_{\text{eff}} |\psi\rangle = \int \prod_i dx_i H_{\text{eff}} \psi(x_1, \dots, x_n, t) a_{x_1}^\dagger \dots a_{x_n}^\dagger |0\rangle$$

$$= \int \prod_i dx_i (i\hbar \partial_t \psi(x_1, \dots, x_n, t)) a_{x_1}^\dagger \dots a_{x_n}^\dagger |0\rangle$$

$$= i\hbar \partial_t |\psi\rangle$$

Since the creation/annihilation operators have no time dependence in the Schrödinger picture.

$$\begin{aligned} \mathcal{L} / [A, BC] &= ABC - BCA \\ &= ABC - BAC - BCA + BAC \\ &= [A, B]C + B[A, C] \end{aligned}$$

$$\begin{aligned} [A, BCDE] &= [A, BC]DE + BC[A, DE] && \text{(using the previous result)} \\ &= [A, B]CDE + B[A, C]DE + BC[A, D]E + BCDAE && \text{replacing } B \rightarrow BC, C \rightarrow DE \\ & && \text{(again).} \end{aligned}$$

Now, let's calculate $[N, a_x]$ and $[N, a_x^\dagger]$.

$$\begin{aligned} [N, a_x] &= \left[\int dy a_y^\dagger a_y, a_x \right] = - \int dy [a_x, a_y^\dagger] a_y = - \int dy [a_x, a_y^\dagger] a_y - \int dy a_y^\dagger [a_x, a_y] \\ &= -a_x \end{aligned}$$

$$\begin{aligned} [N, a_x^\dagger] &= \text{(previous with } a_x \rightarrow a_x^\dagger) = - \int dy [a_x^\dagger, a_y^\dagger] a_y - \int dy a_y^\dagger [a_x^\dagger, a_y] \\ &= +a_x \end{aligned}$$

The clever approach below is due to Srednicki.

$$\begin{aligned} [N, a_{x_1}^\dagger \dots a_{x_n}^\dagger] &= [N, a_{x_1}^\dagger] a_{x_2}^\dagger \dots a_{x_n}^\dagger + a_{x_2}^\dagger [N, a_{x_1}^\dagger] a_{x_3}^\dagger \dots a_{x_n}^\dagger + \dots + a_{x_1}^\dagger \dots a_{x_{n-1}}^\dagger [N, a_{x_n}^\dagger] \\ &= n a_{x_1}^\dagger \dots a_{x_n}^\dagger \quad (\text{of course, since there are } n \text{ particles}) \end{aligned}$$

Similarly $[N, a_{x_1} \dots a_{x_m}] = -m a_{x_1} \dots a_{x_m}$ (|| since $a_{x_1} \dots a_{x_m}$ removes m particles from the state)

$$\begin{aligned} \Rightarrow [N, a_{x_1}^\dagger \dots a_{x_n}^\dagger a_{y_1} \dots a_{y_m}] &= [N, a_{x_1}^\dagger \dots a_{x_n}^\dagger] a_{y_1} \dots a_{y_m} + a_{x_1}^\dagger \dots a_{x_n}^\dagger [N, a_{y_1} \dots a_{y_m}] \\ &= (n-m) a_{x_1}^\dagger \dots a_{x_n}^\dagger a_{y_1} \dots a_{y_m} \end{aligned}$$

Since H only contains terms with $n=m$ (other $n=m=1$, or 2 in the case of the V term), its commutator $[N, H] = 0 \Rightarrow N$ is constant in time. In general, $[N, H] \neq 0$.